

INTERNATIONAL ORGANISATION FOR STANDARDISATION
ORGANISATION INTERNATIONALE DE NORMALISATION
ISO/IEC JTC1/SC29/WG11
CODING OF MOVING PICTURES AND AUDIO

ISO/IEC JTC1/SC29/WG11 MPEG/m52513
January 2020, Brussels, Belgium

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| <i>Source:</i> | Apple Inc. | |
| <i>Status:</i> | Input document | |
| <i>Title:</i> | CE13.6 report on nearest neighbour search order | |
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Abstract

This document reports on the performance of the proposed neighbour search order used in constructing levels of detail for attribute coding as part of core experiment 13.6 [1, N18905].

Introduction

The mandate of the core experiment is to evaluate the LoD construction method [2] and to —

- examine the coding efficiency of the proposed method.
- examine the complexity of the proposed method.

Implementation

The implementation is available in the [mpeg128/ce13.6/nn-search-order](#) branch of the CE repository and is split into two parts. First the neighbour update function is refactored to remove duplicate code. This is non-normative and serves to make the second part, the search order change, more readable.

The change to the search order in LoD construction is such that, neighbours in subsequent LoDs with the same distance from the current point are ordered first by direction, neighbours in the same LoD with the same distance from the current point are searched in forward order, and that neighbours in subsequent LoDs have a higher priority than neighbours in the same LoD.

Results

Table 1 shows the performance of the proposed search order change compared to the TMC13v8 anchor [3]. Since the change includes an aspect related to refactoring, the effects of this compared to the same anchor is shown in Table 2.

Table 1 – Performance of the proposed search order compared to TMC13v8.0

| Condition | Class | BPP Ratio [%] | | | BD-Rate [$\Delta\%$] | | | | | | Avg. of ratio maxrssk [%] | | Ratio of avg. runtime [%] | |
|-----------|------------|---------------|--------|-------|------------------------|-----|------|------|-------|------|---------------------------|---------|---------------------------|---------|
| | | Geometry | Colour | Refl | D1 | D2 | Y | Cb | Cr | R | Encoder | Decoder | Encoder | Decoder |
| C1_ai | cat1-A | | | | | | -0.0 | 0.0 | 0.0 | | 100 | 100 | 99 | 98 |
| C1_ai | cat3-fused | | | | | | 0.0 | -0.0 | -0.0 | -0.0 | 100 | 100 | 99 | 100 |
| C1_ai | cat3-frame | | | | | | | | | 0.0 | 100 | 100 | 91 | 90 |
| C1_ai | overall | | | | | | -0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 97 | 96 |
| C2_ai | cat1-A | | | | 0.0 | 0.0 | 0.1 | 0.2 | -0.2 | | 100 | 100 | 100 | 92 |
| C2_ai | cat1-B | | | | 0.0 | 0.0 | | | | | 100 | 100 | 97 | 100 |
| C2_ai | cat3-fused | | | | 0.0 | 0.0 | 0.0 | -0.0 | 0.0 | -0.0 | 100 | 100 | 104 | 97 |
| C2_ai | cat3-frame | | | | 0.0 | 0.0 | | | | 0.0 | 100 | 100 | 98 | 93 |
| C2_ai | overall | | | | 0.0 | 0.0 | 0.1! | 0.2! | -0.1! | 0.0 | 100 | 100 | 99 | 96 |
| CW_ai | cat1-A | 100.0 | 100.0 | | | | | | | | 100 | 100 | 99 | 99 |
| CW_ai | cat1-B | 100.0 | | | | | | | | | 100 | 100 | 97 | 97 |
| CW_ai | cat3-fused | 100.0 | 100.0 | 100.0 | | | | | | | 100 | 100 | 91 | 94 |
| CW_ai | cat3-frame | 100.0 | | 100.0 | | | | | | | 100 | 100 | 87 | 87 |
| CW_ai | overall | 100.0 | 100.0! | 100.0 | | | | | | | 100 | 100 | 96 | 96 |
| CY_ai | cat1-A | | | | | | 0.0 | 0.0 | 0.0 | | 100 | 100 | 99 | 96 |
| CY_ai | cat3-fused | | | | | | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 94 | 97 |
| CY_ai | cat3-frame | | | | | | | | | 0.0 | 100 | 100 | 100 | 100 |
| CY_ai | overall | | | | | | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 99 | 97 |

NOTE — Condition CY metrics reported using Hausdorff PSNR.

Table 2 – Effect of refactoring compared to TMC13v8.0

| Condition | Class | BPP Ratio [%] | | | BD-Rate [$\Delta\%$] | | | | | | Avg. of ratio maxrssk [%] | | Ratio of avg. runtime [%] | |
|-----------|------------|---------------|--------|-------|------------------------|-----|------|------|------|-----|---------------------------|---------|---------------------------|---------|
| | | Geometry | Colour | Refl | D1 | D2 | Y | Cb | Cr | R | Encoder | Decoder | Encoder | Decoder |
| C1_ai | cat1-A | | | | | | 0.0 | 0.0 | 0.0 | | 100 | 100 | 100 | 100 |
| C1_ai | cat3-fused | | | | | | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 100 | 100 |
| C1_ai | cat3-frame | | | | | | | | | 0.0 | 100 | 100 | 97 | 96 |
| C1_ai | overall | | | | | | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 99 | 99 |
| C2_ai | cat1-A | | | | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | | 100 | 100 | 102 | 100 |
| C2_ai | cat1-B | | | | 0.0 | 0.0 | | | | | 100 | 100 | 98 | 97 |
| C2_ai | cat3-fused | | | | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 106 | 102 |
| C2_ai | cat3-frame | | | | 0.0 | 0.0 | | | | 0.0 | 100 | 100 | 98 | 99 |
| C2_ai | overall | | | | 0.0 | 0.0 | 0.0! | 0.0! | 0.0! | 0.0 | 100 | 100 | 100 | 99 |
| CW_ai | cat1-A | 100.0 | 100.0 | | | | | | | | 100 | 100 | 100 | 105 |
| CW_ai | cat1-B | 100.0 | | | | | | | | | 100 | 100 | 98 | 100 |
| CW_ai | cat3-fused | 100.0 | 100.0 | 100.0 | | | | | | | 100 | 100 | 103 | 95 |
| CW_ai | cat3-frame | 100.0 | | 100.0 | | | | | | | 100 | 100 | 93 | 93 |
| CW_ai | overall | 100.0 | 100.0! | 100.0 | | | | | | | 100 | 100 | 98 | 101 |
| CY_ai | cat1-A | | | | | | 0.0 | 0.0 | 0.0 | | 100 | 100 | 100 | 99 |
| CY_ai | cat3-fused | | | | | | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 96 | 97 |
| CY_ai | cat3-frame | | | | | | | | | 0.0 | 100 | 100 | 106 | 107 |
| CY_ai | overall | | | | | | 0.0 | 0.0 | 0.0 | 0.0 | 100 | 100 | 101 | 101 |

NOTE — Condition CY metrics reported using Hausdorff PSNR.

References

- [1] 3DG, “CE4FE 13.6 Attribute LOD generation,” ISO/IEC JTC1/SC29/WG11, 128th meeting, Geneva, Tech. Rep. w18905, Oct. 2019.
- [2] Z. Gao, D. Flynn, A. Tourapis, and K. Mammou, “[G-PCC][New proposal] Improved implementation of the Prediction and Lifting schemes,” ISO/IEC JTC1/SC29/WG11, 128th meeting, Geneva, Tech. Rep. m51010, Oct. 2019.
- [3] 3DG, “Common Test Conditions for PCC,” ISO/IEC JTC1/SC29/WG11, 128th meeting, Geneva, Tech. Rep. w18883, Oct. 2019.